

Amendments to the claims:

This listing of claims will replace all prior versions, and listings, of claims in the application:

Listing of Claims:

1. CANCELLED

2. (Currently amended) A metrology tool for aligning a robot having an engagement member for engaging a semiconductor substrate carrier disposed on a tool load-port, comprising:

a frame having an opening; and

a removable alignment gauge member slidably received in said frame opening, said alignment gauge member having an opening to receive said robot engagement member when inserted in said frame opening, The tool of claim 4 wherein

said alignment gauge member has a front face positioned to be engaged by said robot engagement member when said robot engagement member is misaligned with respect to said alignment gauge member opening, said alignment gauge member being adapted to slide when said alignment gauge member front face is engaged by said robot engagement member.

3. (Currently amended) The tool of claim 4 2 wherein said robot engagement member is a registration pin and said alignment gauge member opening is sized and shaped to receive said registration pin when said alignment gauge member opening is aligned with respect to said registration pin.

4. (Original) The tool of claim 3 wherein said alignment gauge member opening is cylindrically shaped.

5. (Currently amended) The tool of claim 4 2 wherein said frame opening is cylindrically shaped and said removable alignment gauge member has a cylindrically shaped

portion adapted to be slidably received by said frame opening.

6. (Currently amended) The tool of claim 4 2 wherein said robot engagement member is a door key and said alignment gauge member opening is sized and shaped to receive said door key when said alignment gauge member opening is aligned with respect to said door key.

7. (Original) The tool of claim 6 wherein said alignment gauge member opening is rectangularly shaped.

8. (Currently amended) The tool of claim 6 wherein said frame opening is cylindrically shaped and said removable alignment gauge member has a cylindrically shaped portion adapted to be slidably received by said frame opening, said frame further having one of an alignment pin and an alignment pin hole and said alignment gauge member having the other of said alignment pin and ~~an~~ said alignment pin hole wherein said alignment pin hole is positioned to align said alignment gauge member to said frame when said alignment pin is received in said alignment pin hole.

9. (Currently amended) The tool of claim 4 2 further comprising a plurality of removable alignment and support receptacles fastened to said frame and positioned to support said frame on said tool load-port.

10. (Original) The tool of claim 9 wherein each of said receptacles has four alignment surfaces and said frame has four alignment surfaces for each receptacle, each frame alignment surface being positioned to be engaged by an associated receptacle alignment surface to align the frame and associated receptacle when fastened to the frame.

11. (Currently amended) The tool of claim 10 wherein each receptacle has a block-shaped portion which provides said four receptacle alignment surfaces, and wherein said frame has an aperture for each receptacle ~~receptacles~~ wherein each frame aperture defines said four frame alignment surfaces which are positioned to receive and align an associated receptacle

portion.

12. (Original) The tool of claim 11 further comprising a plurality of removable fasteners for fastening each removable receptacle to said frame when said receptacle block-shaped portion is received in said frame aperture.

13. (Currently amended) The tool of claim 4 2 wherein said frame includes a base plate, a frame plate carried by said base plate, and a removable door plate releasably fastened to said frame plate wherein said door plate defines said frame opening.

14. (Original) The tool of claim 13 wherein said frame further includes a plurality of alignment pins adapted to align said door plate to said frame plate when said door plate is fastened to said frame plate.

15. (Currently amended) The tool of claim 4 2 wherein said frame opening defines a central axis and said alignment gauge member opening defines a central axis offset with respect to said frame opening central axis, said alignment gauge member being adapted for rotation in said frame opening about said frame opening axis.

16. (Original) The tool of claim 15 wherein said alignment gauge member has a first indicia and said frame has a second indicia adjacent said frame opening, said first and second indicia being adapted to provide an indication of the rotational position of said alignment gauge member within said frame opening.

17. (Original) The tool of claim 16 wherein at least one of said indicia include angular position indicia expressed in degrees.

18. (Original) A metrology tool for aligning a door-opening robot having a pair of registration pins and a pair of latch keys for engaging a pair of registration pin holes and a pair of latch key holes, respectively of a plastic door of a plastic Front-Opening Universal Pod (FOUP) having three plastic receptacles, each receptacle adapted to be disposed on an alignment and

support coupling pin of a tool load-port of a factory interface, said metrology tool comprising:

a metal frame having a metal base plate having three metal receptacles, each receptacle configured and positioned to emulate one of said FOUP receptacles, said frame further having a metal front plate carried by said base plate, and a pair of metal side brace members, each adapted to brace said front plate with respect to said base plate, said front plate defining at least four cylindrical openings;

first and second cylindrical metal removable registration pin alignment members, each registration pin alignment member being slidably received in a front plate opening and having a cylindrical opening sized and shaped to emulate a FOUP registration pin hole and to receive a robot registration pin when said registration pin alignment member opening is aligned with respect to a robot registration pin, each registration pin alignment member further having a front face positioned to be engaged by a robot registration pin when a robot registration pin is misaligned with respect to the associated registration pin alignment member opening, said registration pin alignment member being adapted to slide when said registration pin alignment member front face is engaged by a robot registration pin; and

first and second cylindrical metal removable latch key alignment members, each latch key alignment member being slidably received in a front plate opening and having a rectangular opening sized and shaped to emulate a FOUP latch key hole and to receive a robot latch key when said latch key alignment member opening is aligned with respect to a robot latch key, each latch key alignment member further having a front face positioned to be engaged by a robot latch key when a robot latch key is misaligned with respect to the associated latch key alignment member opening, said latch key alignment member being adapted to slide when said latch key alignment member front face is engaged by a robot latch key.

19. CANCELLED

20. (Currently amended) A metrology tool kit for aligning a robot having an engagement member for engaging a semiconductor substrate carrier disposed on a load port tool, comprising

a frame having an opening; and

a plurality of removable alignment gauge members, each alignment gauge

member being adapted to be selectably inserted and removed from said frame opening one at a time, each member having an opening to receive said robot engagement member when inserted in said frame opening wherein said member openings differ in size, The tool kit of claim 19
wherein

a first alignment gauge member of said plurality has a member opening of a first size and a second alignment gauge member of said plurality has a member opening of a size approximately 100.2% of said first size.

21. (Currently amended) The tool kit of claim 49 20 wherein a first alignment gauge member of said plurality has a member opening of a first size and a second alignment gauge member of said plurality has a member opening of a size approximately 104% of said first size.

22. (Currently amended) The tool kit of claim 49 20 wherein a first alignment gauge member of said plurality has a member opening of a first size and a second alignment gauge member of said plurality has a member opening of a size approximately 108% of said first size.

23. (Original) A metrology tool for aligning a robot having a pair of registration pins and a pair of latch keys for engaging a door of a substrate carrier disposed on a tool load-port, comprising:

a frame adapted to be disposed in said tool-load port and having at least four openings;
first and second removable registration pin alignment members, each registration pin alignment member being slidably received in a frame opening and having an opening sized and shaped to receive a robot registration pin when said registration pin alignment member opening is aligned with respect to a robot registration pin, each registration pin alignment member further having a front face positioned to be engaged by a robot registration pin when a robot registration pin is misaligned with respect to the associated registration pin alignment member opening, said registration pin alignment member being adapted to slide when said registration pin alignment member front face is engaged by a robot registration pin; and

first and second removable latch key alignment members, each latch key

alignment member being slidably received in a frame opening and having an opening sized and shaped to receive a robot latch key when said latch key alignment member opening is aligned with respect to a robot latch key, each latch key alignment member further having a front face positioned to be engaged by a robot latch key when a robot latch key is misaligned with respect to the associated latch key alignment member opening, said latch key alignment member being adapted to slide when said latch key alignment member front face is engaged by a robot latch key.

24. (Currently amended) A metrology tool for aligning a robot having a carrier door key for unlatching a carrier door of a substrate carrier disposed on a tool load-port, comprising:

carrier frame emulation means for resting on said tool load-port and for emulating a substrate carrier frame; and

door emulation means carried by said carrier frame emulation means for emulating a door of said substrate carrier, said door emulation means having an opening and a removable alignment gauge means slidably carried in said door emulation means opening for gauging alignment of a robot carrier door key, said alignment gauge means including opening means for emulating a door key opening, wherein said alignment gauge opening means receives said robot carrier door key when said alignment gauge opening means is carried in alignment with said robot carrier door key and wherein said alignment gauge means slides in response to being engaged by said robot ~~door~~ carrier door key when said alignment gauge means opening is carried in misalignment with said robot carrier door key.

25. (Currently amended) A method of aligning a robot engagement member to a door opening of a carrier door of a substrate carrier disposed on a tool load-port, comprising:

disposing a frame emulating a carrier frame on said tool load-port;

placing a first alignment gauge insert into an opening in said frame; and

driving said robot engagement member toward said alignment gauge insert wherein an opening in said alignment gauge insert receives said robot engagement member when said alignment gauge insert opening is in alignment with said robot engagement member and wherein said alignment gauge insert slides in response to being engaged by said robot engagement member when said alignment gauge insert opening is misaligned with said robot

engagement member.

26. (Currently amended) The method of claim 25 wherein said robot engagement member is a registration pin and said alignment gauge ~~member~~ insert opening is sized and shaped to receive said registration pin when said alignment gauge ~~member~~ insert opening is aligned with respect to said registration pin.

27. (Currently amended) The method of claim 26 wherein said robot engagement member is a door key and said alignment gauge ~~member~~ insert opening is sized and shaped to receive said door key when said alignment gauge ~~member~~ insert opening is aligned with respect to said door key.

28. (Original) The method of claim 25 further comprising removing an alignment and support receptacle from said frame; fastening a substitute alignment and support receptacle to said frame; and positioning said frame substitute alignment and support receptacle on said tool load-port.

29. (Original) The method of claim 28 further comprising engaging four alignment surfaces of said substitute receptacle with four alignment surfaces of said frame to align said substitute receptacle with said frame prior to fastening said substitute receptacle to said frame.

30. (Original) The method of claim 29 wherein said substitute receptacle has a block-shaped portion which provides said four receptacle alignment surfaces, and wherein said frame has an aperture which defines said four frame alignment surfaces, said alignment surface engaging including positioning said block-shaped portion of said substitute receptacle in said frame alignment aperture.

31. (Original) The method of claim 30 wherein said fastening comprises fastening removable fasteners fastening said substitute receptacle to said frame when said receptacle block-shaped portion is received in said frame aperture.

32. (Original) The method of claim 25 wherein said frame includes a base plate, a frame plate carried by said base plate, and a removable door plate releasably fastened to said frame plate wherein said door plate defines said frame opening, the method further comprising removing said door plate from said frame plate and fastening a substitute door plate to said frame plate.

33. (Original) The method of claim 32 further comprising aligning said substitute door plate to said frame plate using alignment pins prior to fastening said substitute door plate to said frame plate.

34. (Currently amended) The method of claim 25 further comprising removing said first alignment gauge insert from said frame and placing a substitute alignment gauge insert in said frame opening wherein said substitute alignment gauge insert opening has an opening which is smaller in size than said first alignment gauge insert opening, said method further comprising driving said robot engagement member toward said substitute alignment gauge insert wherein said opening in said substitute alignment gauge receives said robot engagement member when said substitute alignment gauge insert opening is in alignment with said robot engagement member and wherein said substitute alignment gauge insert slides in response to being engaged by said robot engagement member when said alignment gauge insert opening is misaligned with said robot engagement member.

35. (Currently amended) The method of claim 34 wherein said first alignment gauge insert opening is 108% of the size of said substitute alignment gauge insert opening.

36. (Currently amended) The method of claim 34 wherein said first alignment gauge insert opening is 104% of the size of said substitute alignment gauge insert opening.

37. (Currently amended) The method of claim 34 wherein said first alignment gauge insert opening is 100.2% of the size of said substitute alignment gauge insert opening.

38. (Currently amended) The method of claim 25 wherein said frame opening defines a central axis and said alignment gauge ~~member~~ insert opening defines a central axis offset with respect to said frame opening central axis, said alignment gauge ~~member~~ insert being adapted for rotation in said frame opening about said frame opening axis, said method further comprising rotating said alignment gauge ~~member~~ insert in a first rotational direction until said engagement member engages an internal surface of said alignment gauge ~~member~~ insert opening.

39. (Currently amended) The method of claim 38 wherein said alignment gauge ~~member~~ insert has a first indicia and said frame has a second indicia adjacent said frame opening and adapted to provide an indication of the rotational position of said first indicia of said alignment gauge ~~member~~ insert within said frame opening, said method further comprising noting the indicated rotational position when said engagement member engages an internal surface of said alignment gauge ~~member~~ insert opening.

40. (Currently amended) A method of aligning a door-opening robot having a pair of registration pins and a pair of latch keys for engaging a pair of registration pin holes and a pair of latch key holes, respectively of a plastic door of a plastic Front-Opening Universal Pod (FOUP) having three plastic receptacles, each receptacle adapted to be disposed on an alignment and support coupling pin of a tool load-port of a factory interface, comprising:

disposing a metal frame having three metal receptacles on a plurality of alignment and support coupling pins of a tool load-port of a factory interface, each receptacle configured and positioned to emulate one of said FOUP receptacles on said tool load-port;

placing a metal registration pin alignment gauge insert into an opening in said frame, wherein said registration pin alignment gauge insert has an opening sized and shaped to emulate a FOUP registration pin hole and to receive said robot registration pin when said registration pin alignment gauge insert opening is aligned with respect to said robot registration pin;

driving said robot registration pin toward said registration pin alignment gauge insert wherein said registration pin alignment gauge insert opening receives said robot registration pin when said registration pin alignment gauge insert opening is in alignment with said robot

registration pin and wherein said registration pin alignment gauge insert slides in response to being engaged by said robot registration pin when said registration pin alignment gauge insert opening is misaligned with said robot ~~engagement member~~ registration pin;

placing a metal latch key alignment gauge insert into an opening in said frame, wherein said latch key alignment gauge insert has an opening sized and shaped to emulate a FOUP latch key hole and to receive said robot latch key when said latch key alignment gauge insert opening is aligned with respect to said robot latch key; and

driving said robot latch key toward said latch key alignment gauge insert wherein said latch key alignment gauge insert opening receives said robot latch key when said latch key alignment gauge insert opening is in alignment with said robot a latch key and wherein said latch key alignment gauge insert slides in response to being engaged by said robot latch key when said latch key alignment gauge insert opening is misaligned with said robot ~~engagement member~~ latch key.

41. (Currently amended) A method of aligning a robot registration pin and a robot latch key to a carrier door of a semiconductor substrate carrier disposed on a tool load-port, comprising:

disposing a frame emulating a carrier frame on said tool load-port;

placing a registration pin alignment gauge insert into an opening in said frame, wherein said registration pin alignment gauge insert has an opening sized and shaped to receive said robot registration pin when said registration pin alignment gauge insert opening is aligned with respect to said robot registration pin;

driving said robot registration pin toward said registration pin alignment gauge insert wherein said registration pin alignment gauge insert opening receives said robot registration pin when said registration pin alignment gauge insert opening is in alignment with said robot registration pin and wherein said registration pin alignment gauge insert slides in response to being engaged by said robot registration pin when said registration pin alignment gauge insert opening is misaligned with said robot engagement member;

placing a latch key alignment gauge insert into an opening in said frame, wherein said latch key alignment gauge insert has an opening sized and shaped to receive said robot latch key when said latch key alignment gauge insert opening is aligned with respect to said robot

latch key; and

driving said robot latch key toward said latch key alignment gauge insert wherein said latch key alignment gauge insert opening receives said robot latch key when said latch key alignment gauge insert opening is in alignment with said robot latch key and wherein said latch key alignment gauge insert slides in response to being engaged by said robot latch key when said latch key alignment gauge insert opening is misaligned with said robot engagement member.

42. (Currently amended) A method of aligning a door-opening robot having a pair of registration pins and a pair of latch keys for engaging a pair of registration pin holes and a pair of latch key holes, respectively of a plastic door of a plastic Front-Opening Universal Pod (FOUP) having three plastic receptacles, each receptacle adapted to be disposed on an alignment and support coupling pin of a tool load-port of a factory interface, comprising:

disposing a metal frame having three metal receptacles on a plurality of alignment and support coupling pins of a tool load-port of a factory interface, each receptacle configured and positioned to emulate one of said FOUP receptacles on said tool load-port;

placing a metal registration pin alignment gauge insert into an opening in said frame, wherein said registration pin alignment gauge insert has an opening sized and shaped to emulate a FOUP registration pin hole and to receive said robot registration pin when said registration pin alignment gauge insert opening is aligned with respect to said robot registration pin;

driving said robot registration pin toward said registration pin alignment gauge insert wherein said registration pin alignment gauge insert opening receives said robot registration pin when said registration pin alignment gauge insert opening is in alignment with said robot registration pin and wherein said registration pin alignment gauge insert slides in response to being engaged by said robot registration pin when said registration pin alignment gauge insert opening is misaligned with said robot registration pin engagement member;

placing a metal latch key alignment gauge insert into an opening in said frame, wherein said latch key alignment gauge insert has an opening sized and shaped to emulate a FOUP latch key hole and to receive said robot latch key when said latch key alignment gauge insert opening is aligned with respect to said robot latch key; and

driving said robot latch key toward said latch key alignment gauge insert wherein said latch key alignment gauge insert opening receives said robot latch key when said latch key alignment gauge insert opening is in alignment with said robot a latch key and wherein said latch key alignment gauge insert slides in response to being engaged by said robot latch key when said latch key alignment gauge insert opening is misaligned with said robot latch key engagement member.

43. CANCELLED.

Amendments to the Drawings:

The attached sheet of drawings includes changes to FIG. 1. This sheet which includes FIG. 1 replaces the original sheet including FIG. 1. In FIG. 1, the term "Prior Art" has been added.

The attached sheet of drawings includes changes to FIG. 2. This sheet which includes FIG. 2 replaces the original sheet including FIG. 2. In FIG. 2, the term "Prior Art" has been added.

The attached sheet of drawings includes changes to FIG. 3a. This sheet which includes FIG. 3a replaces the original sheet including FIG. 3a. In FIG. 3a, the reference numbers "510a", "510d", "810b" and "810c" have been added.

Attachments: Three (3) Replacement Sheets

Three (3) Annotated Sheets showing Changes